

Fig. 1

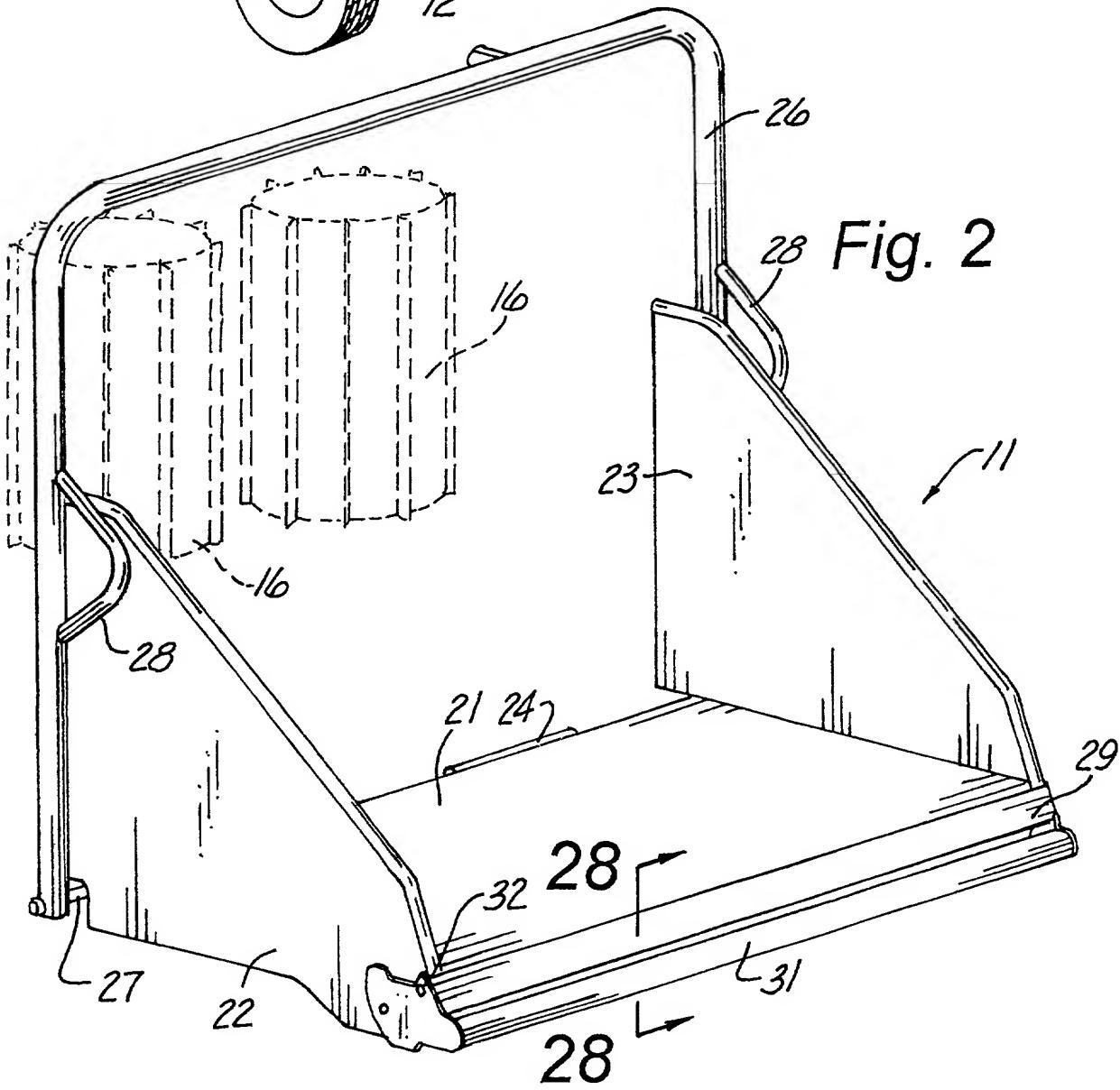
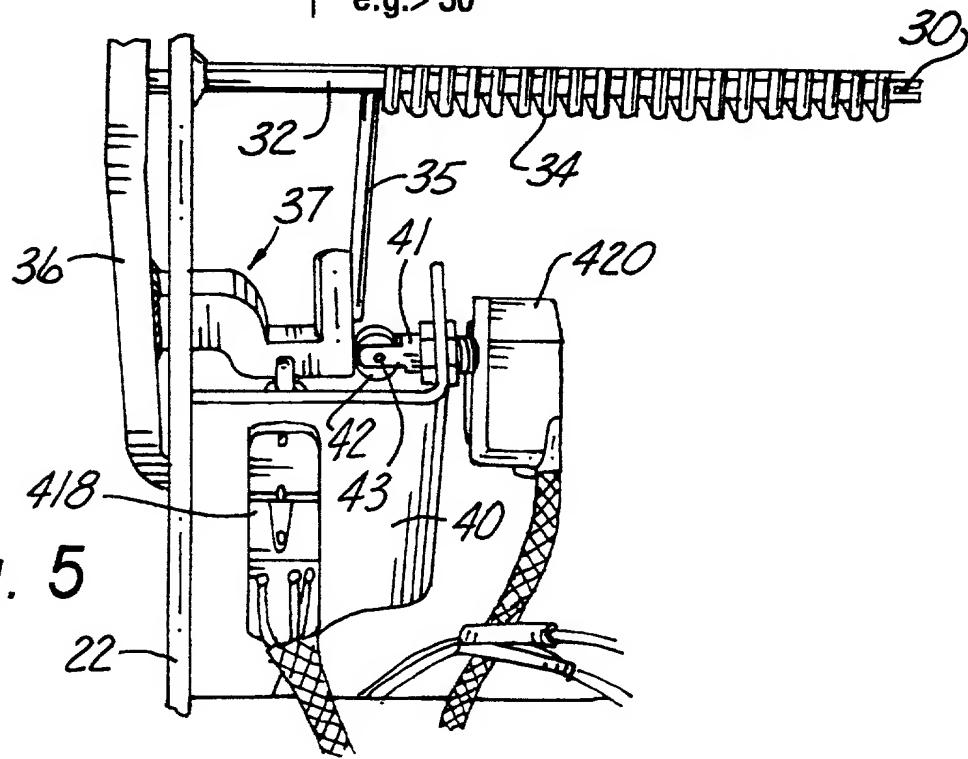
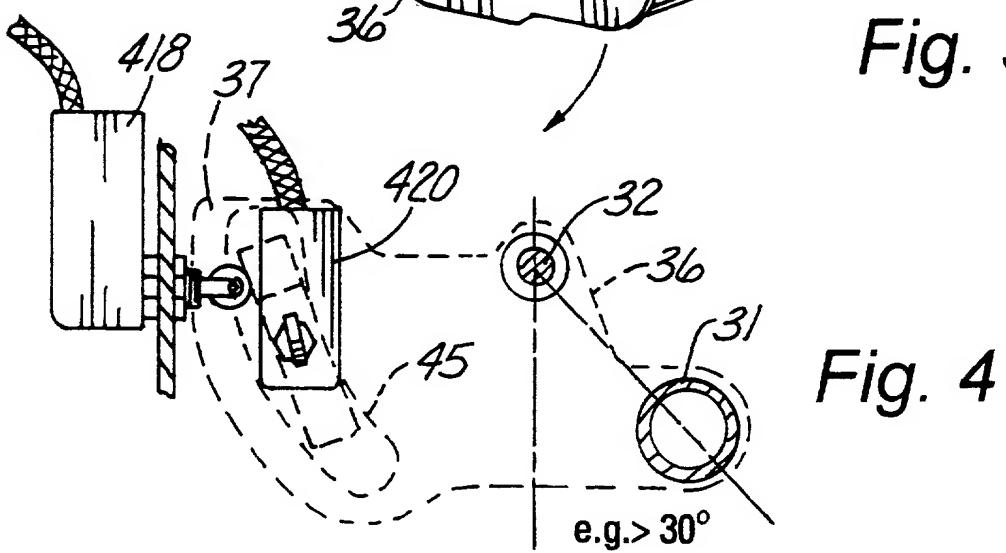
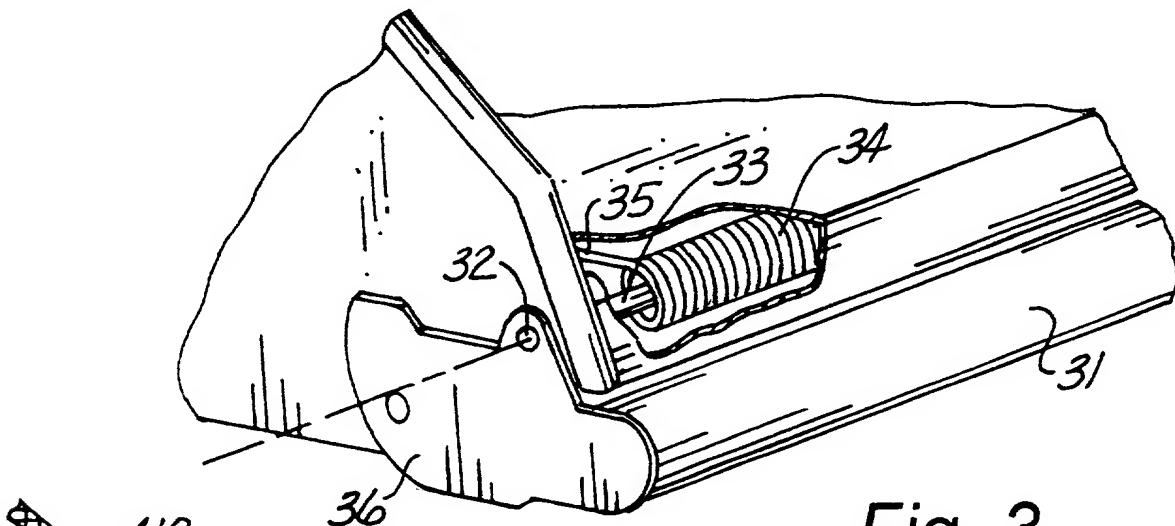
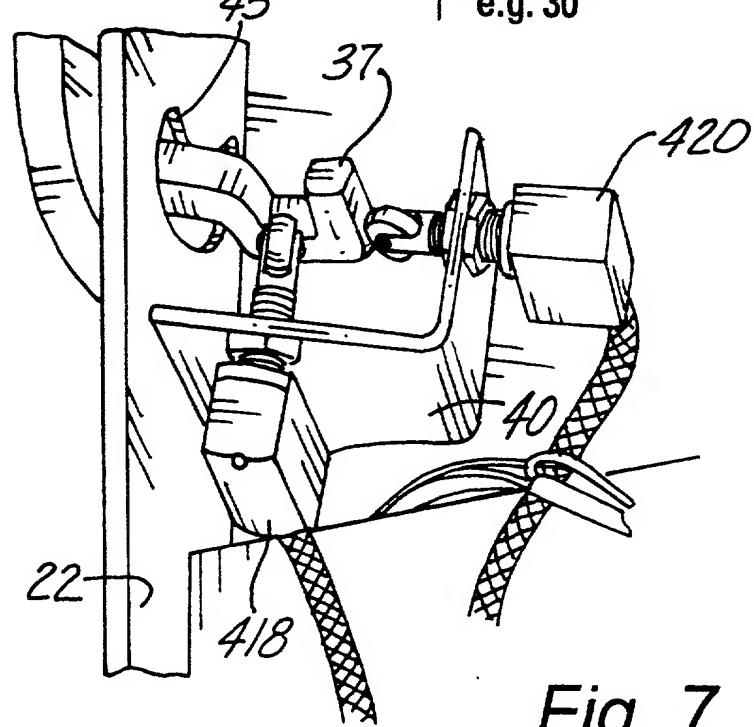
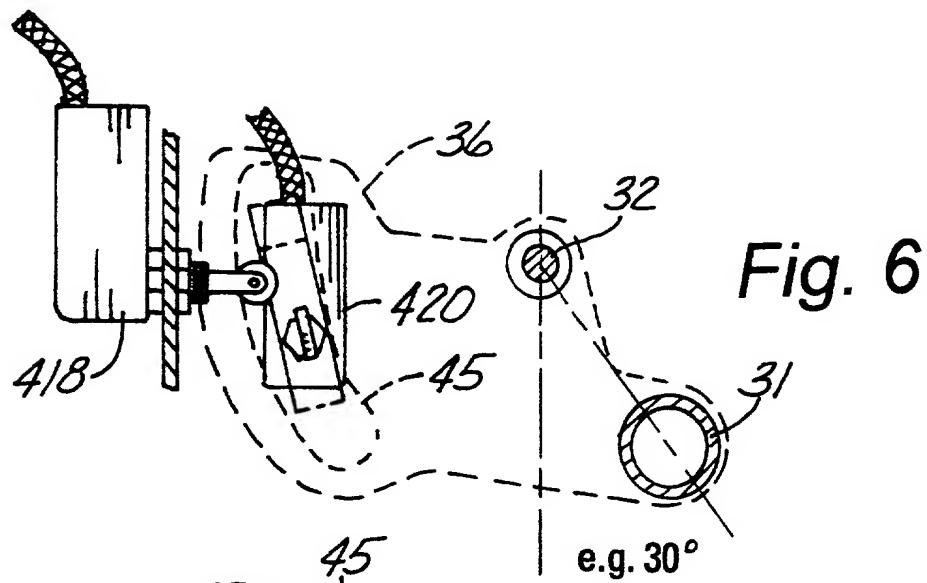
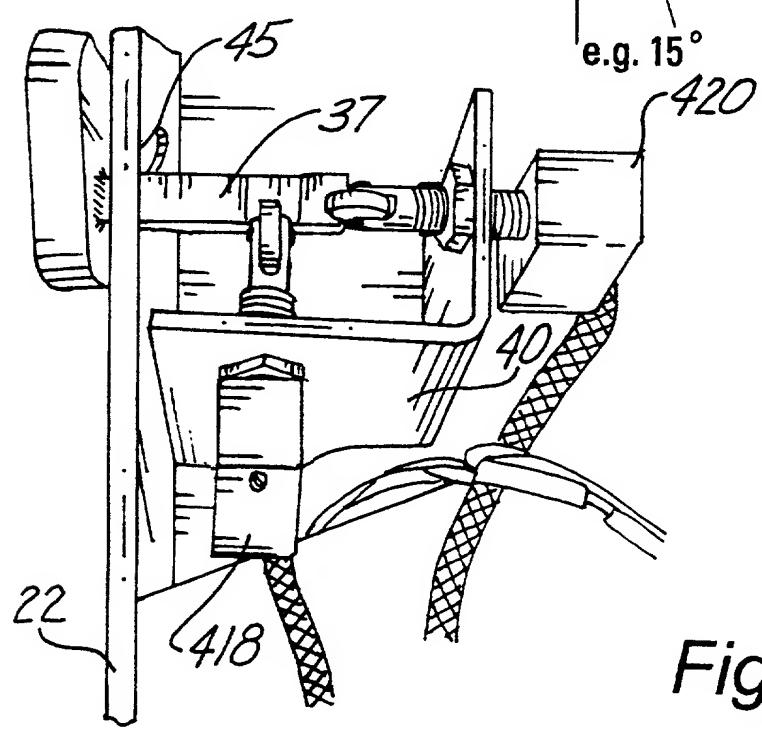
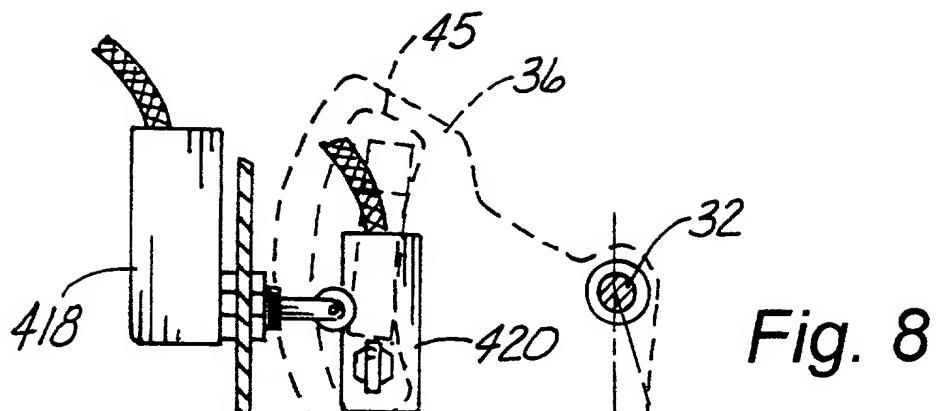


Fig. 2



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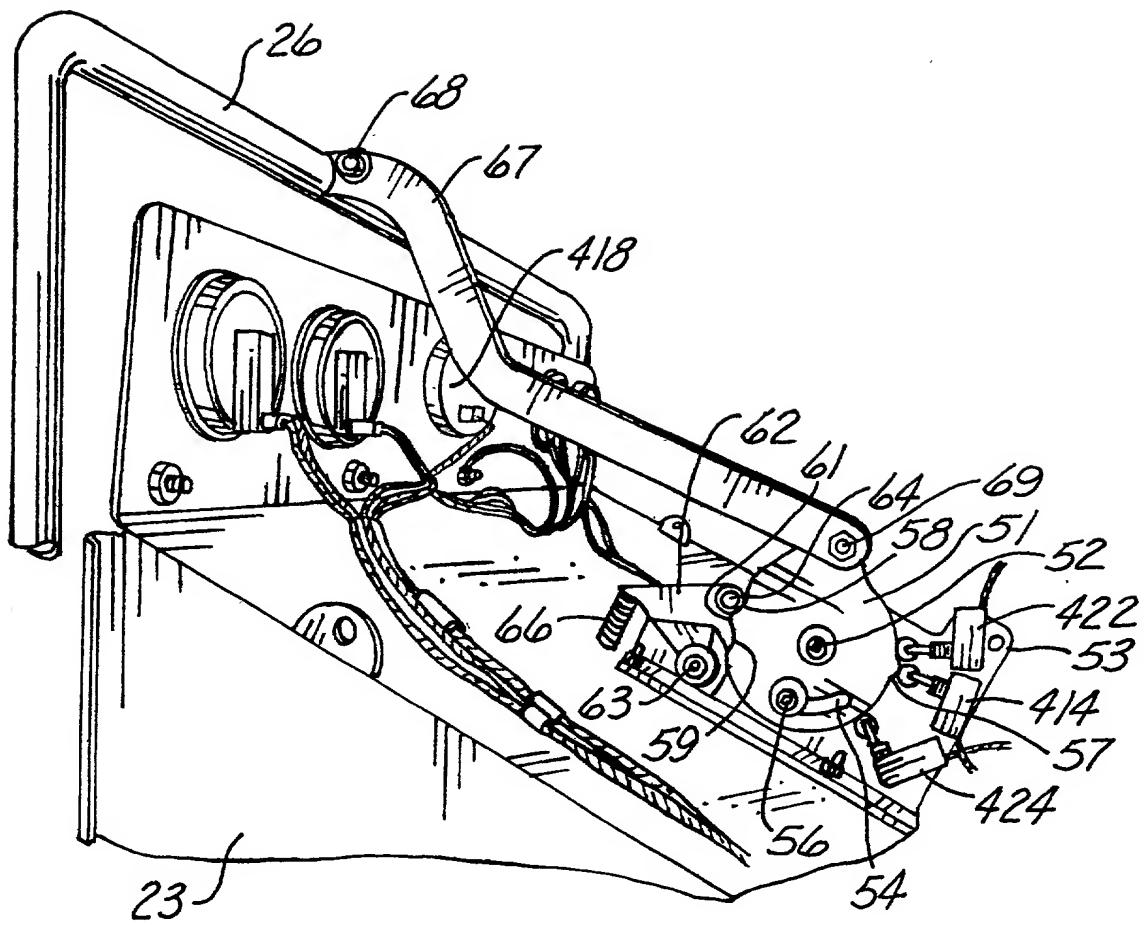


Fig. 10

*Fig. 11* FORWARD FEED

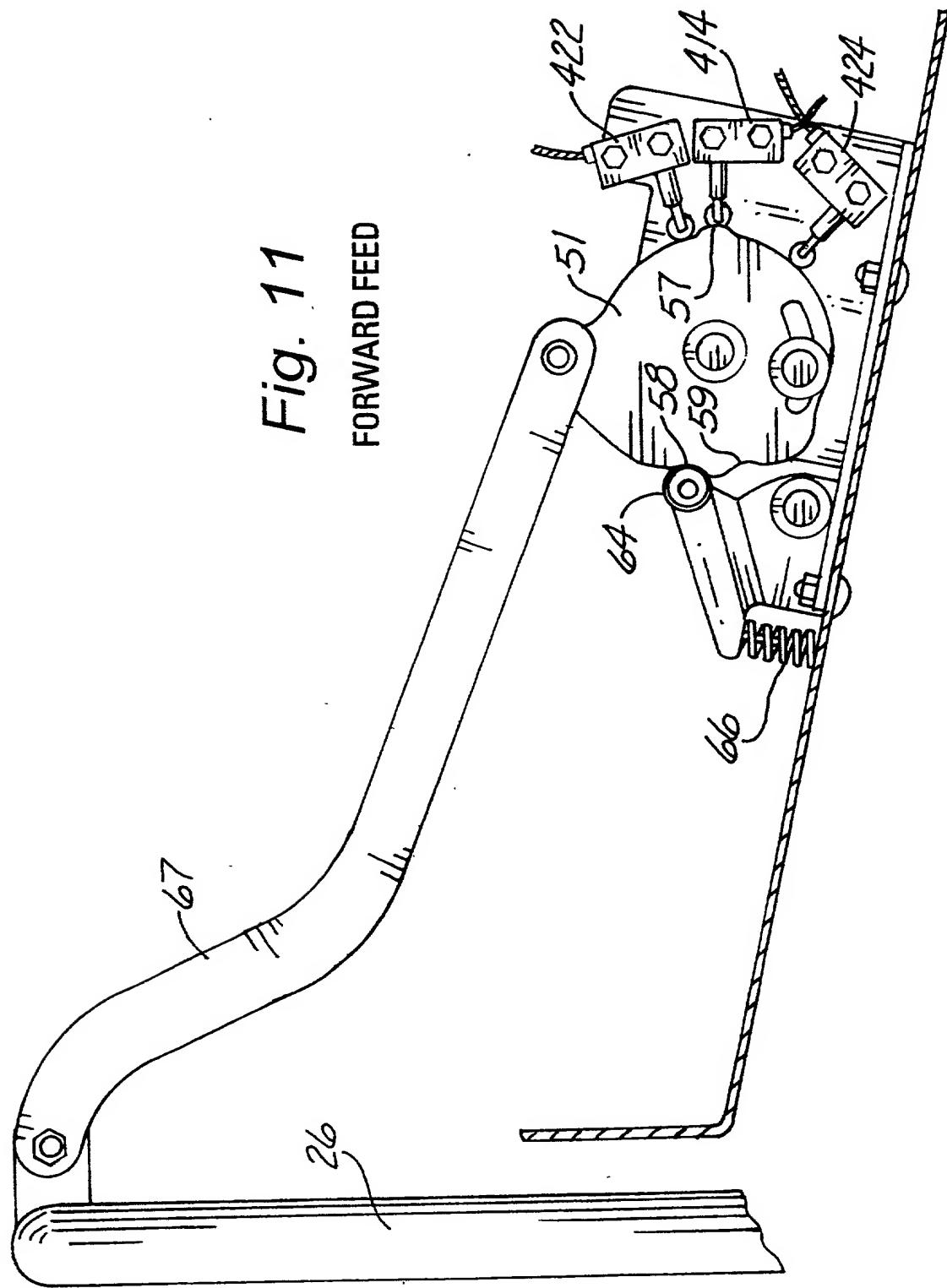


Fig. 12

STOP

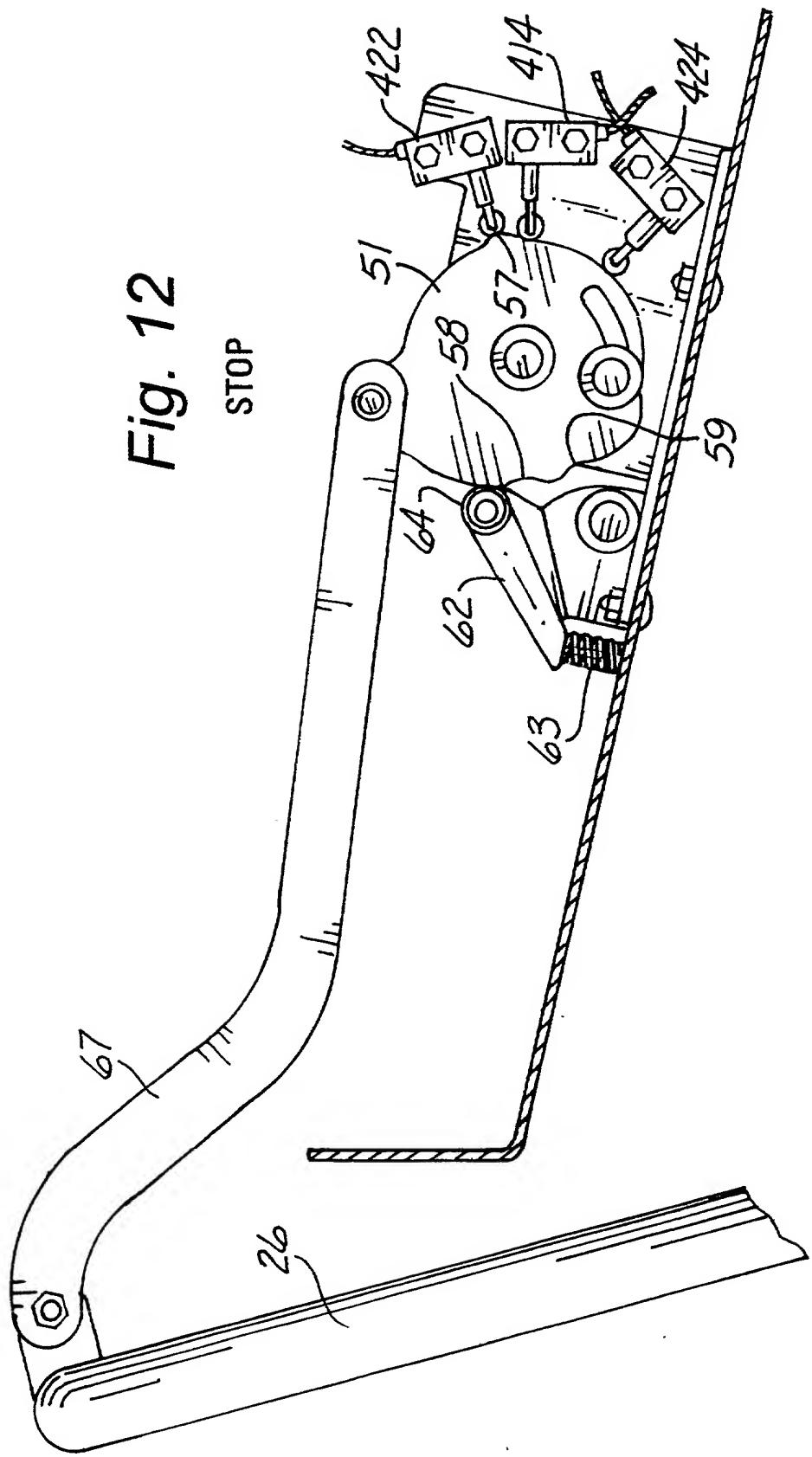


Fig. 13

REVERSE

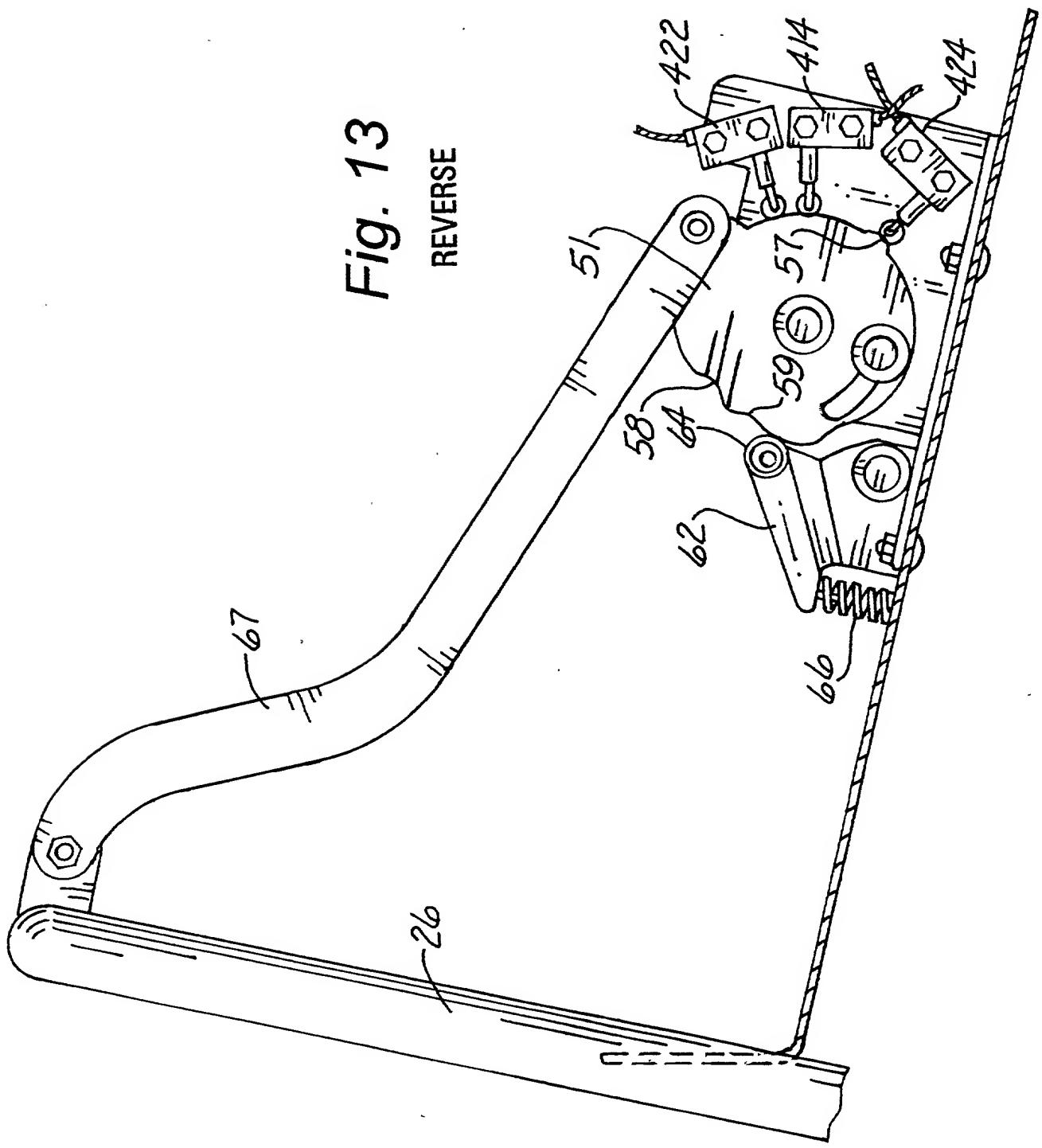
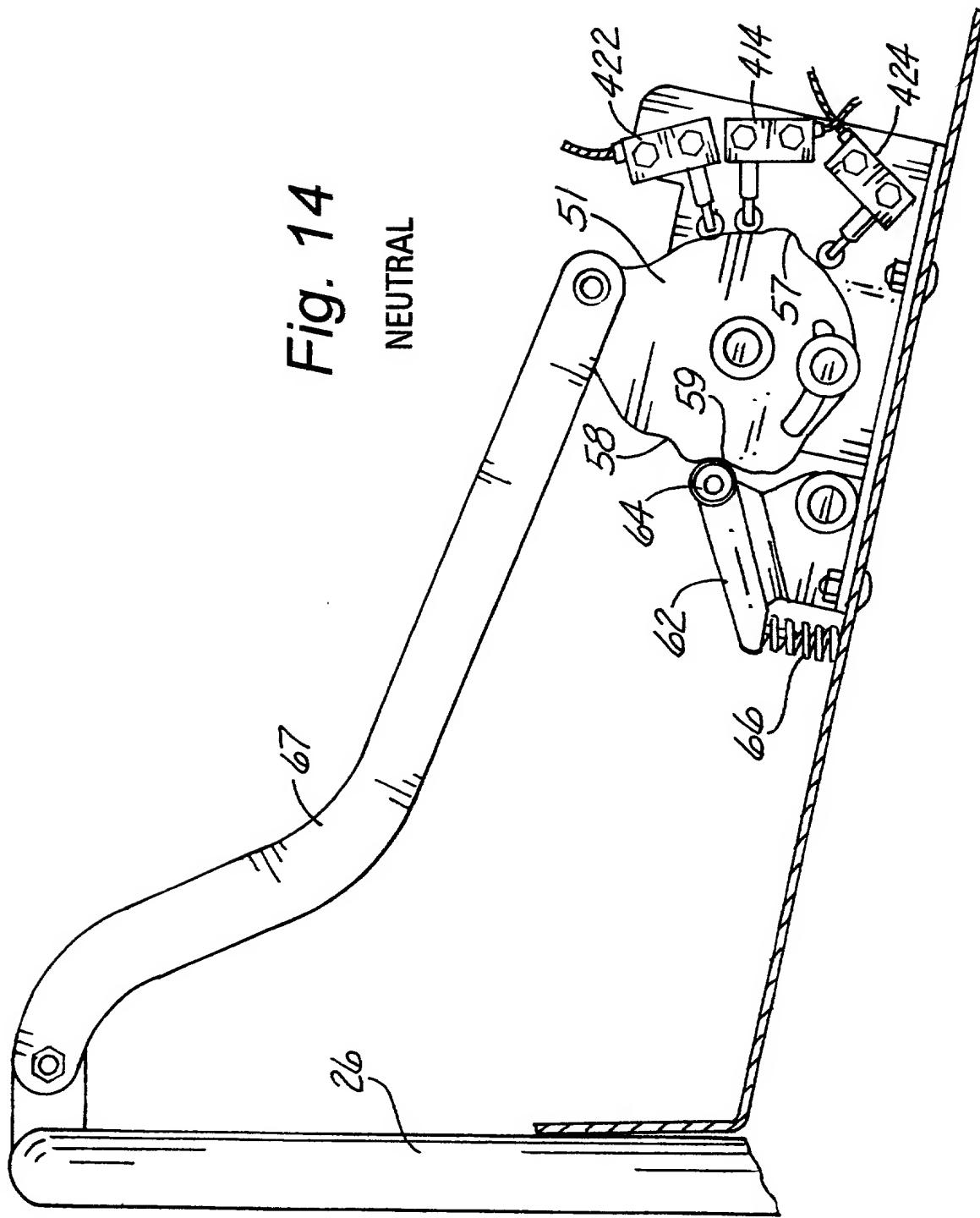


Fig. 14

NEUTRAL



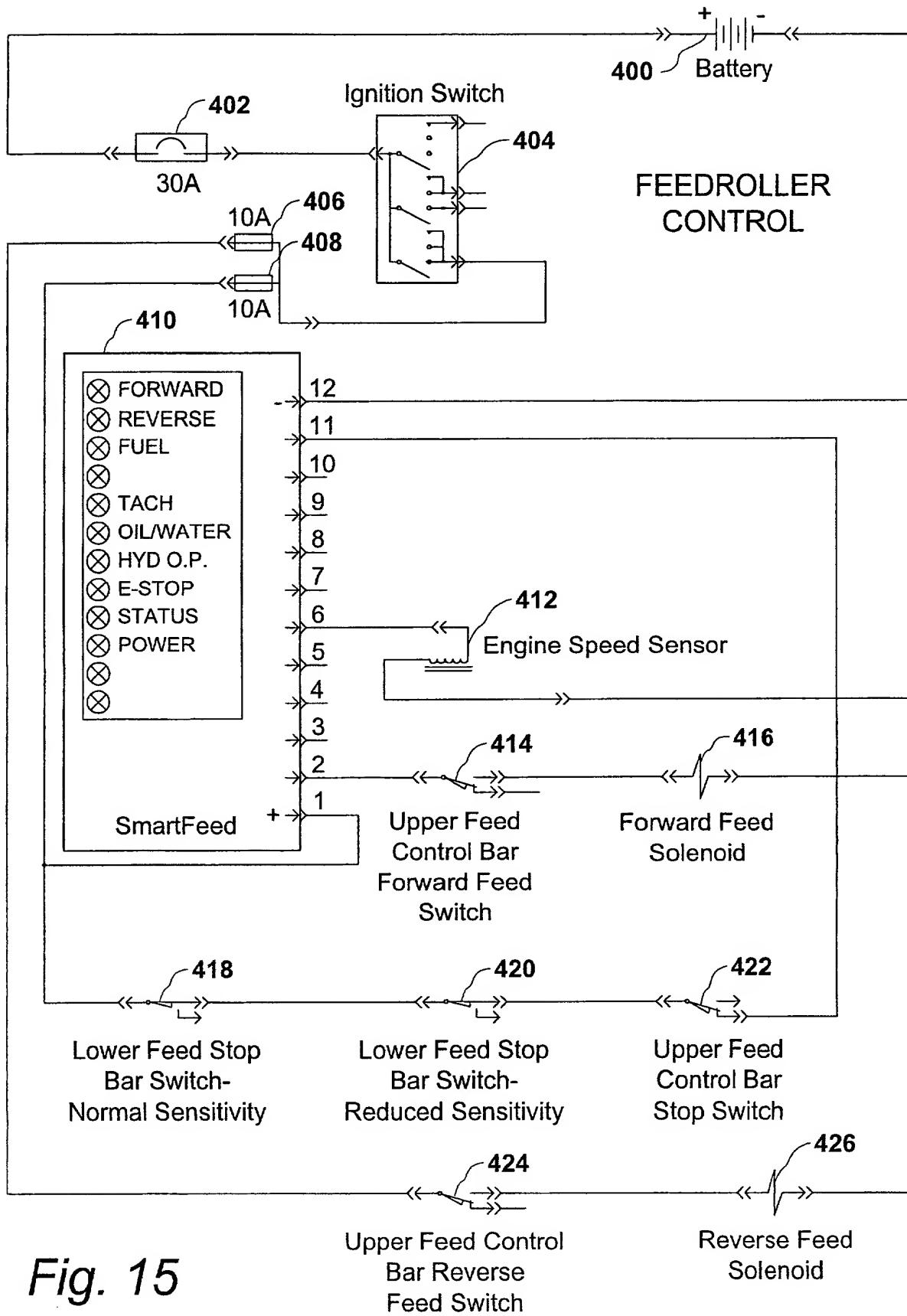


Fig. 15

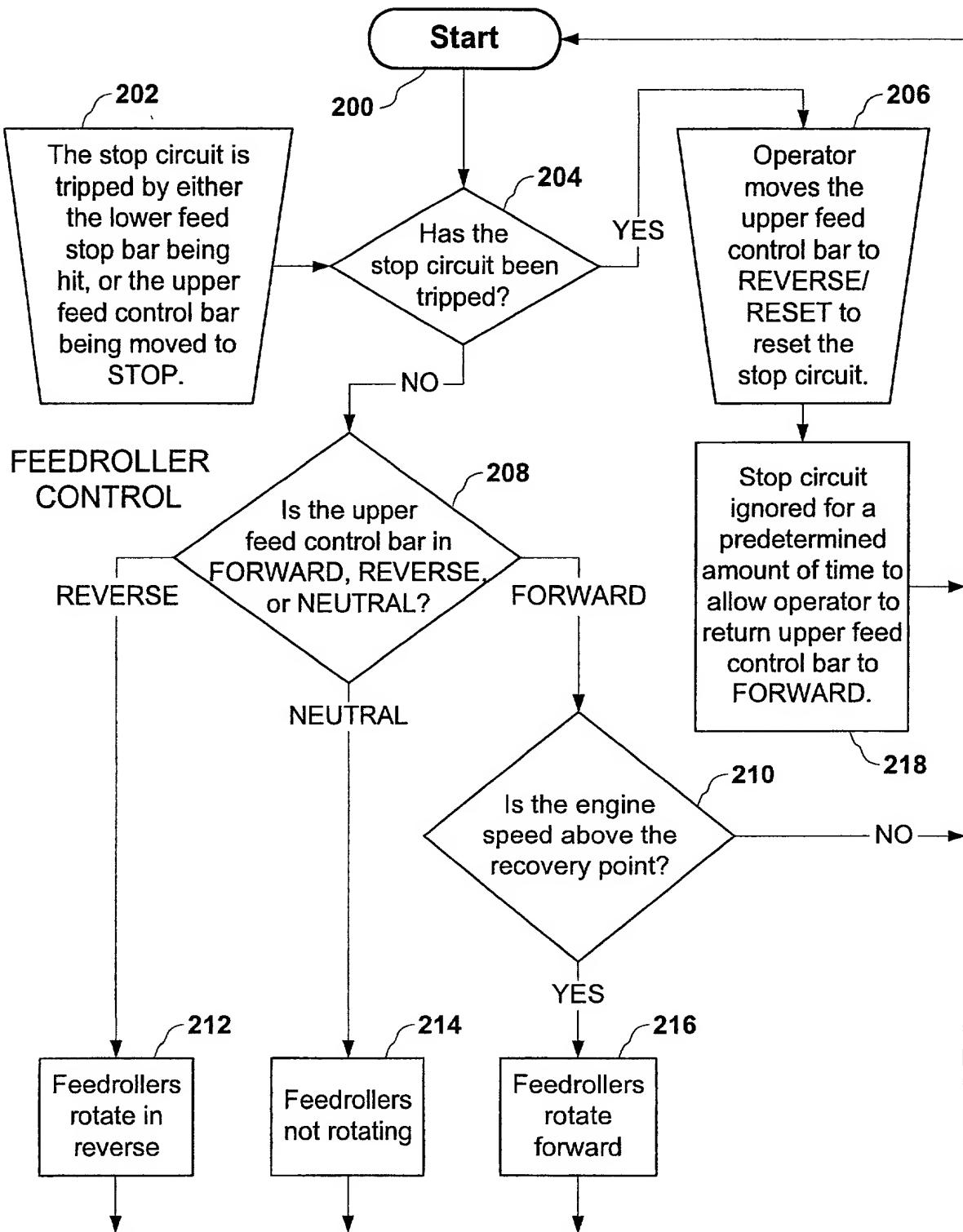


Fig. 16

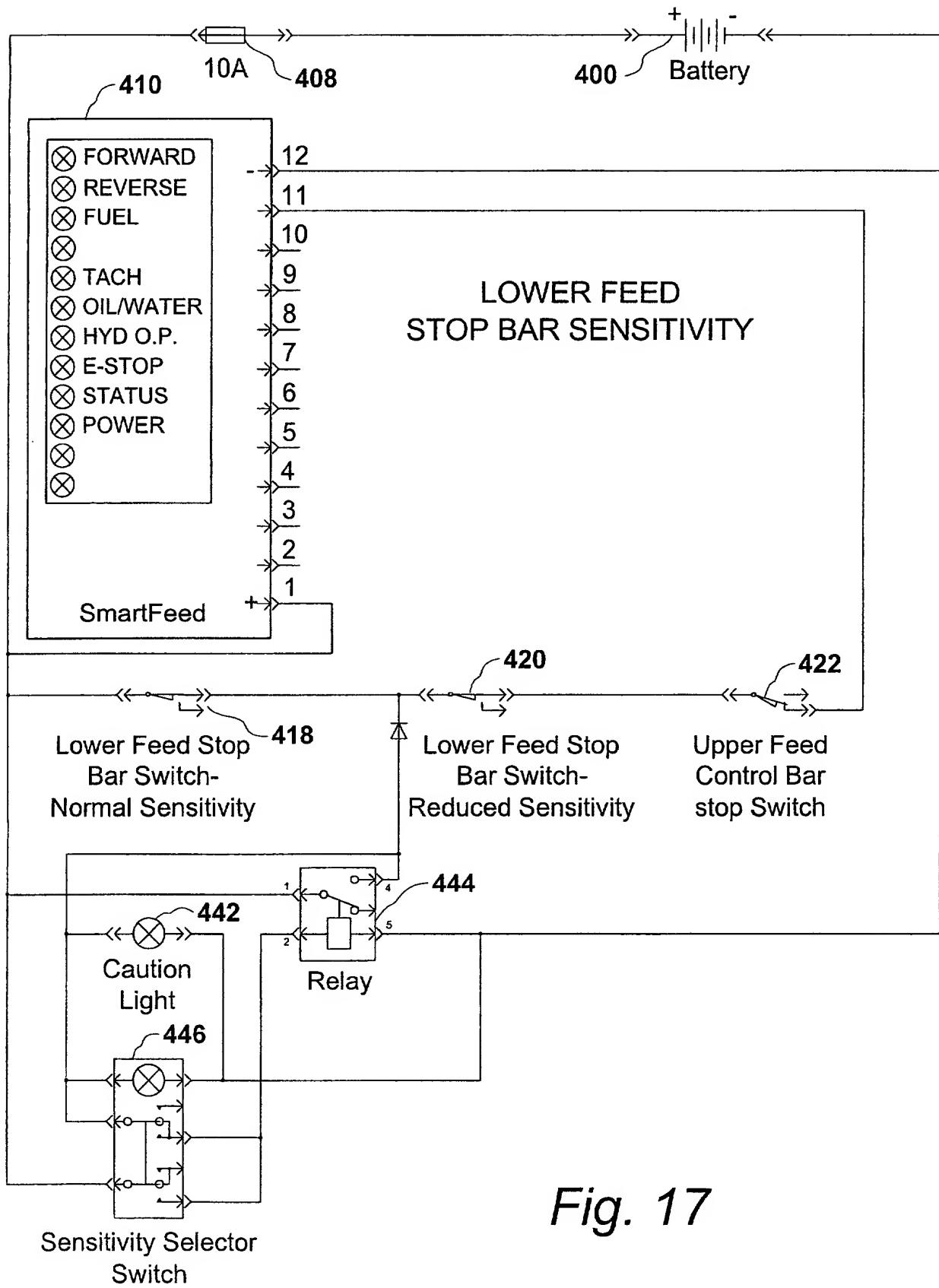


Fig. 17

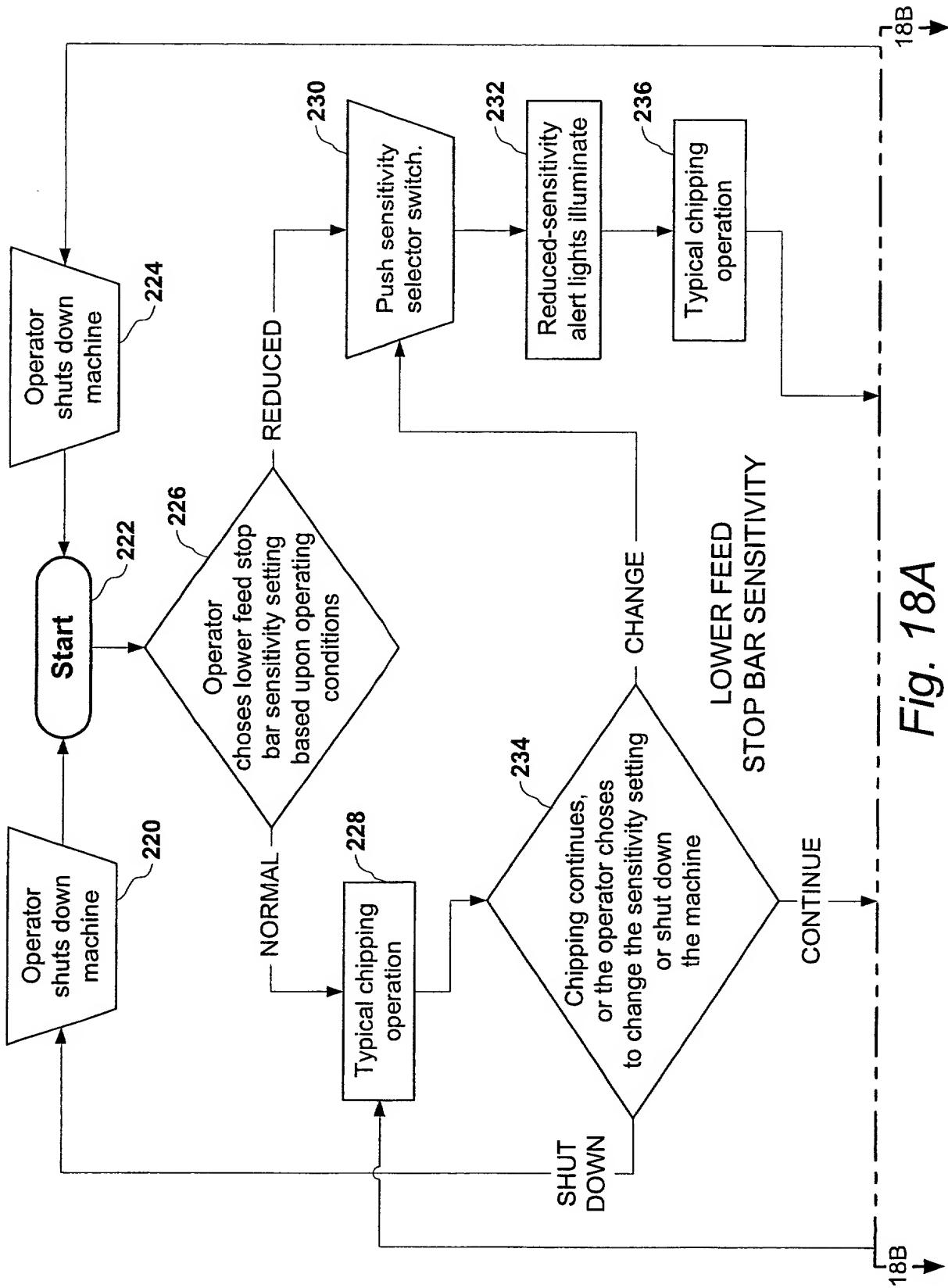
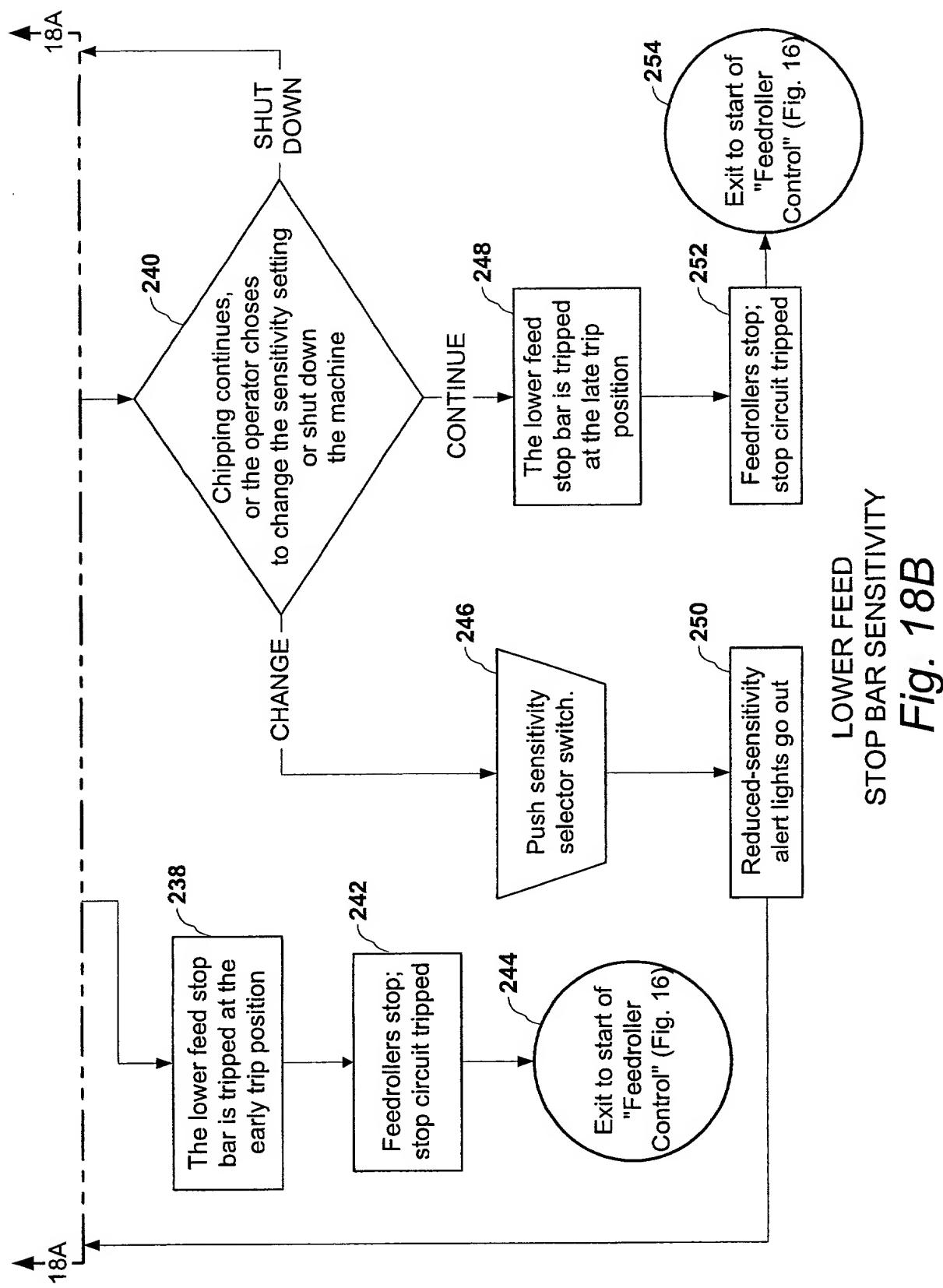


Fig. 18A



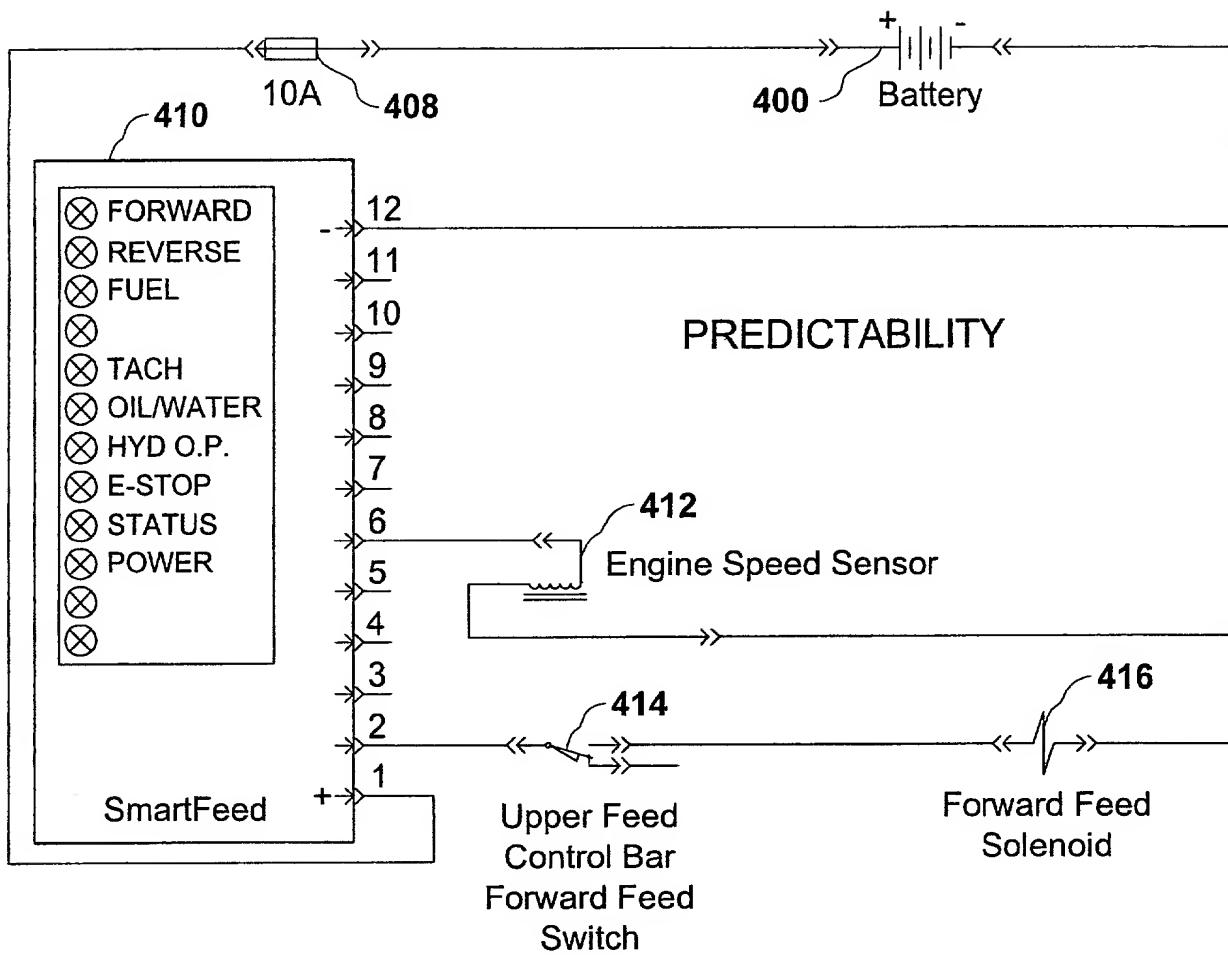


Fig. 19

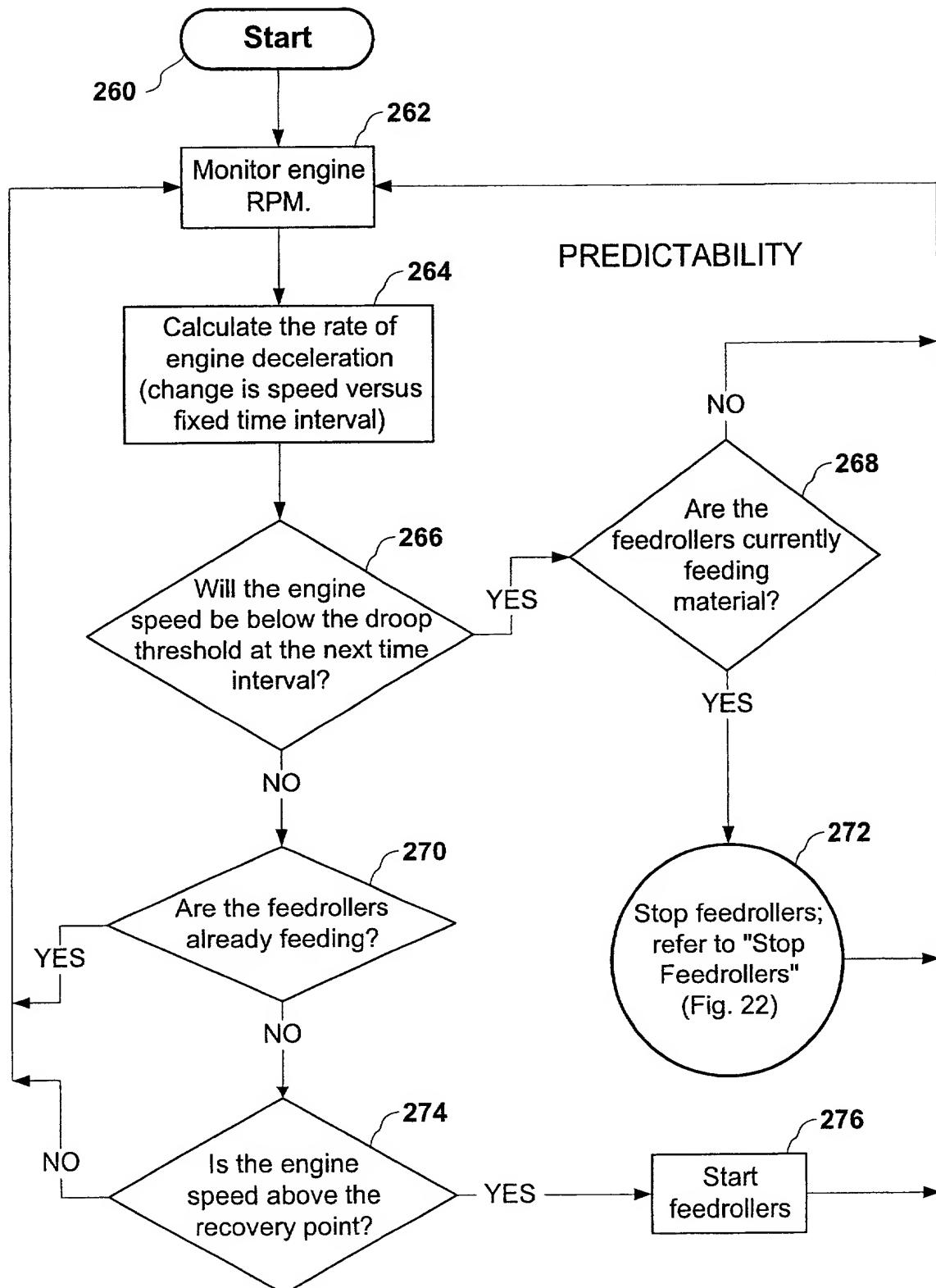


Fig. 20

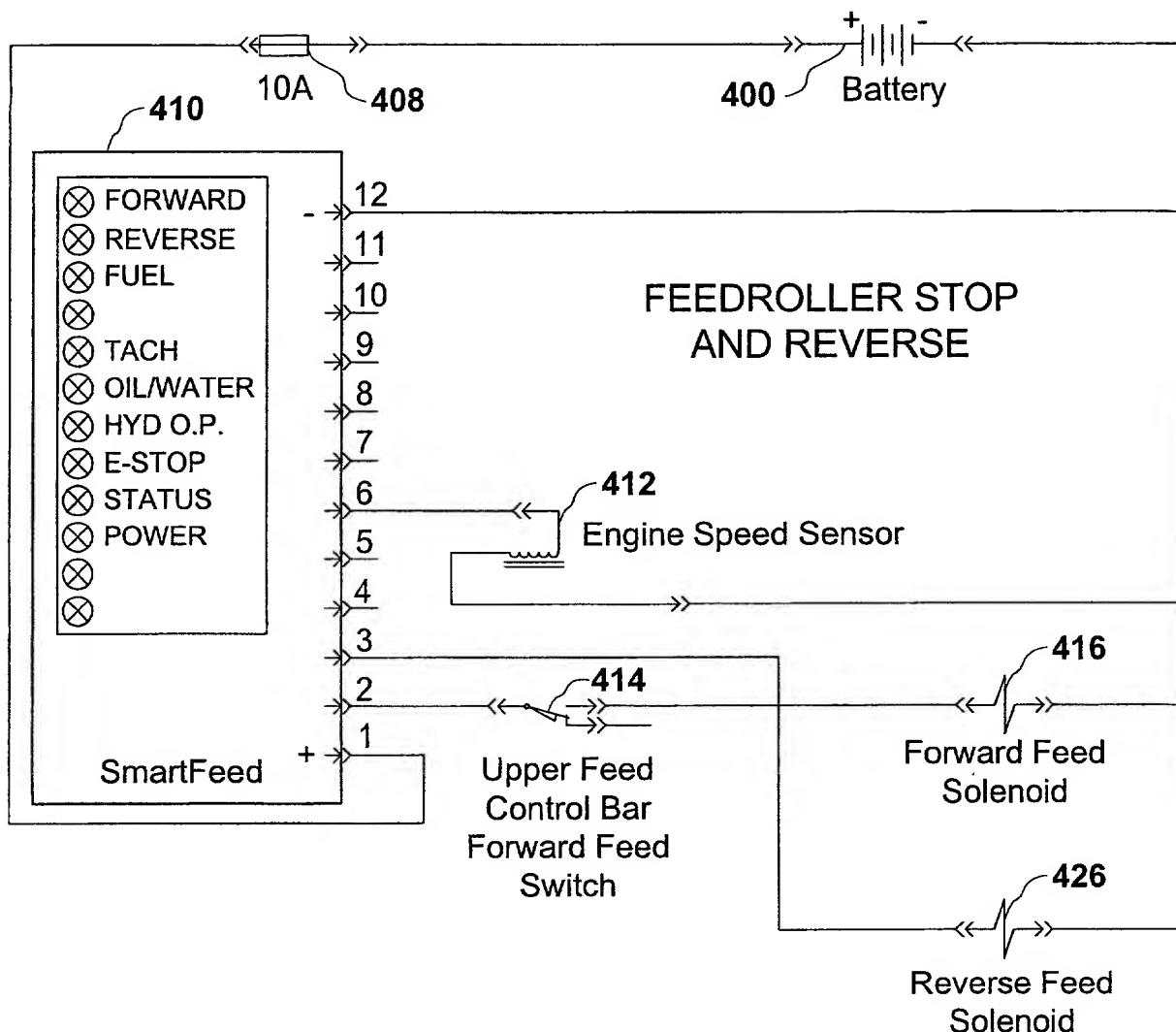


Fig. 21

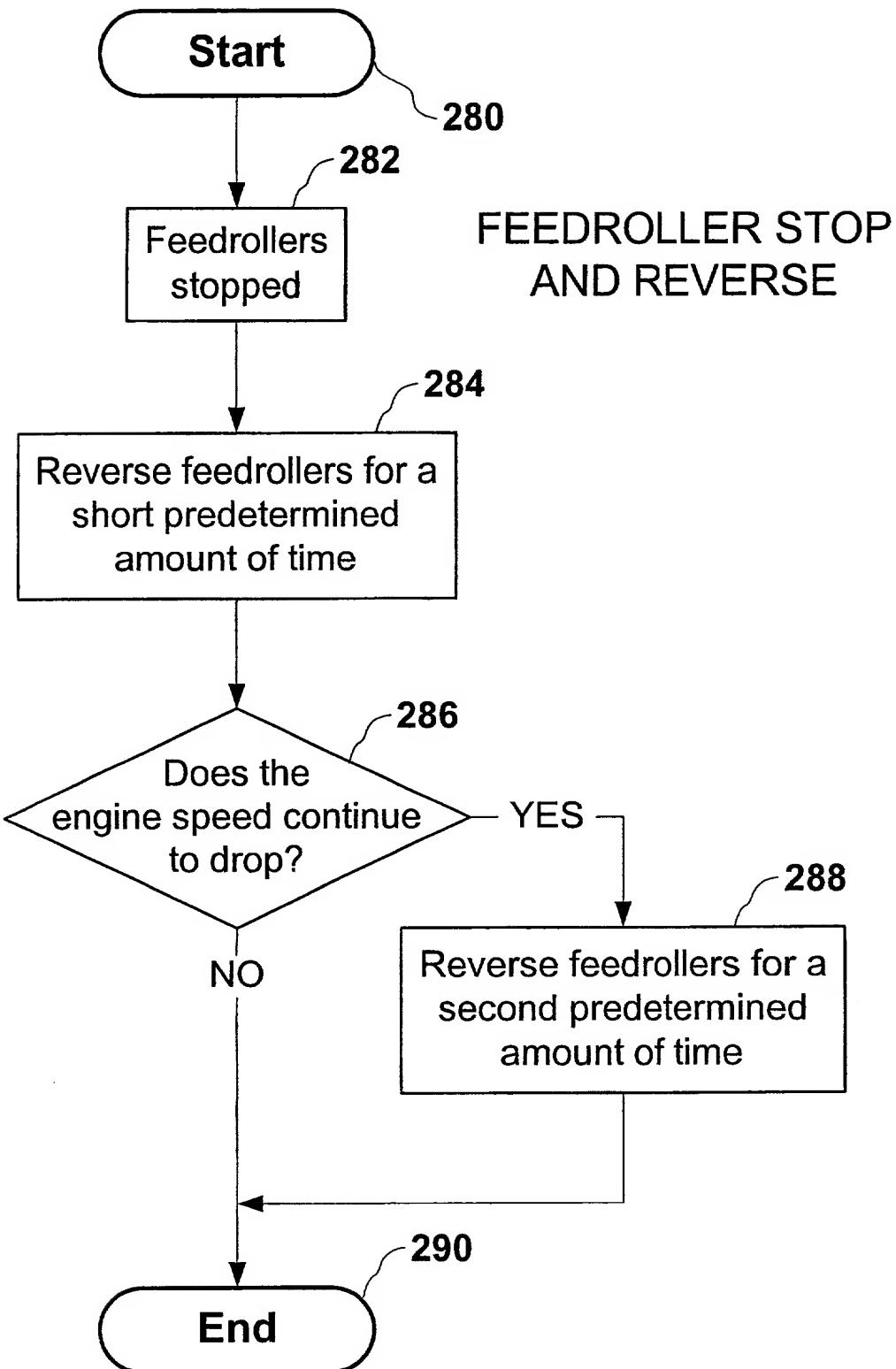


Fig. 22

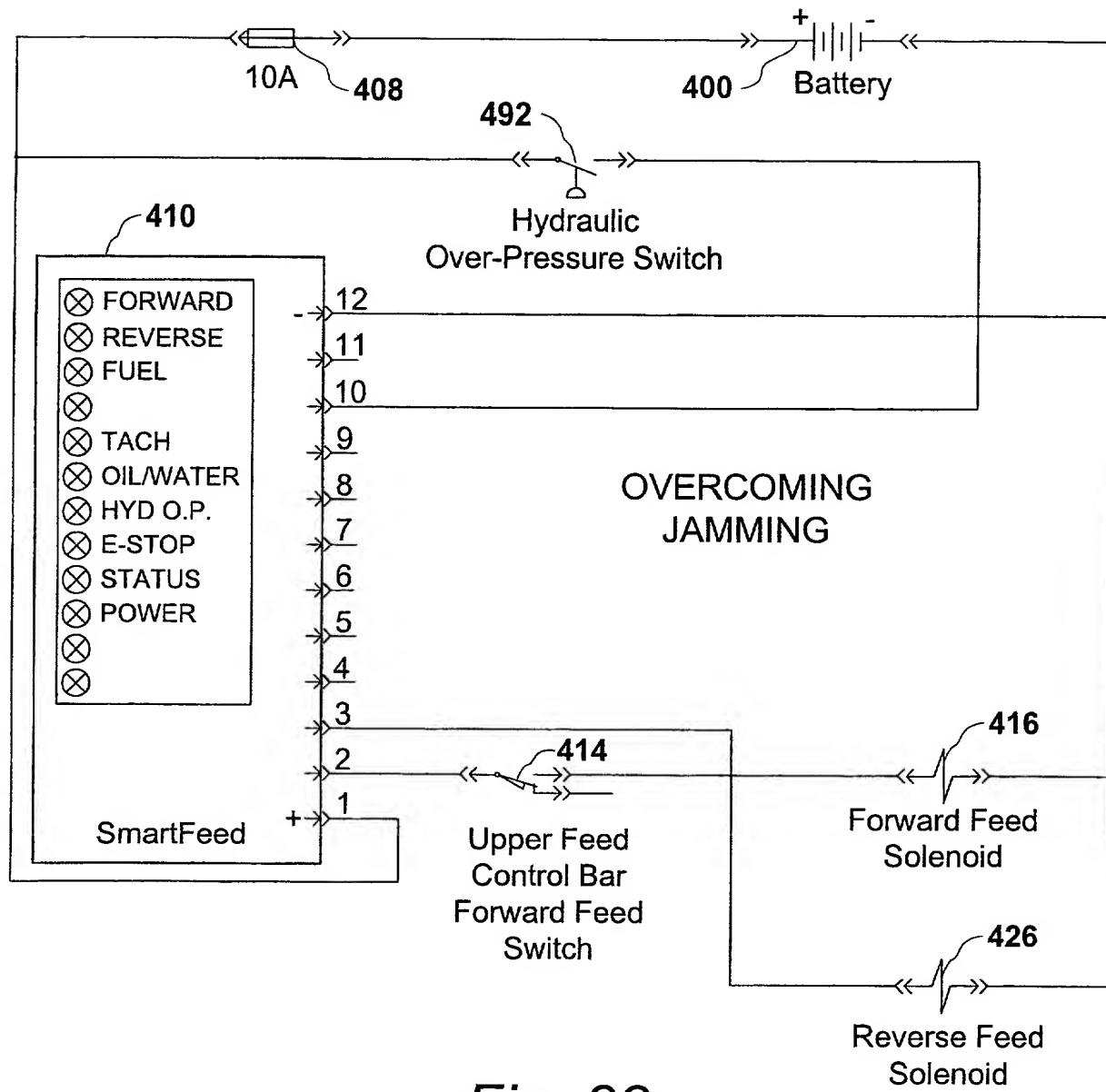


Fig. 23

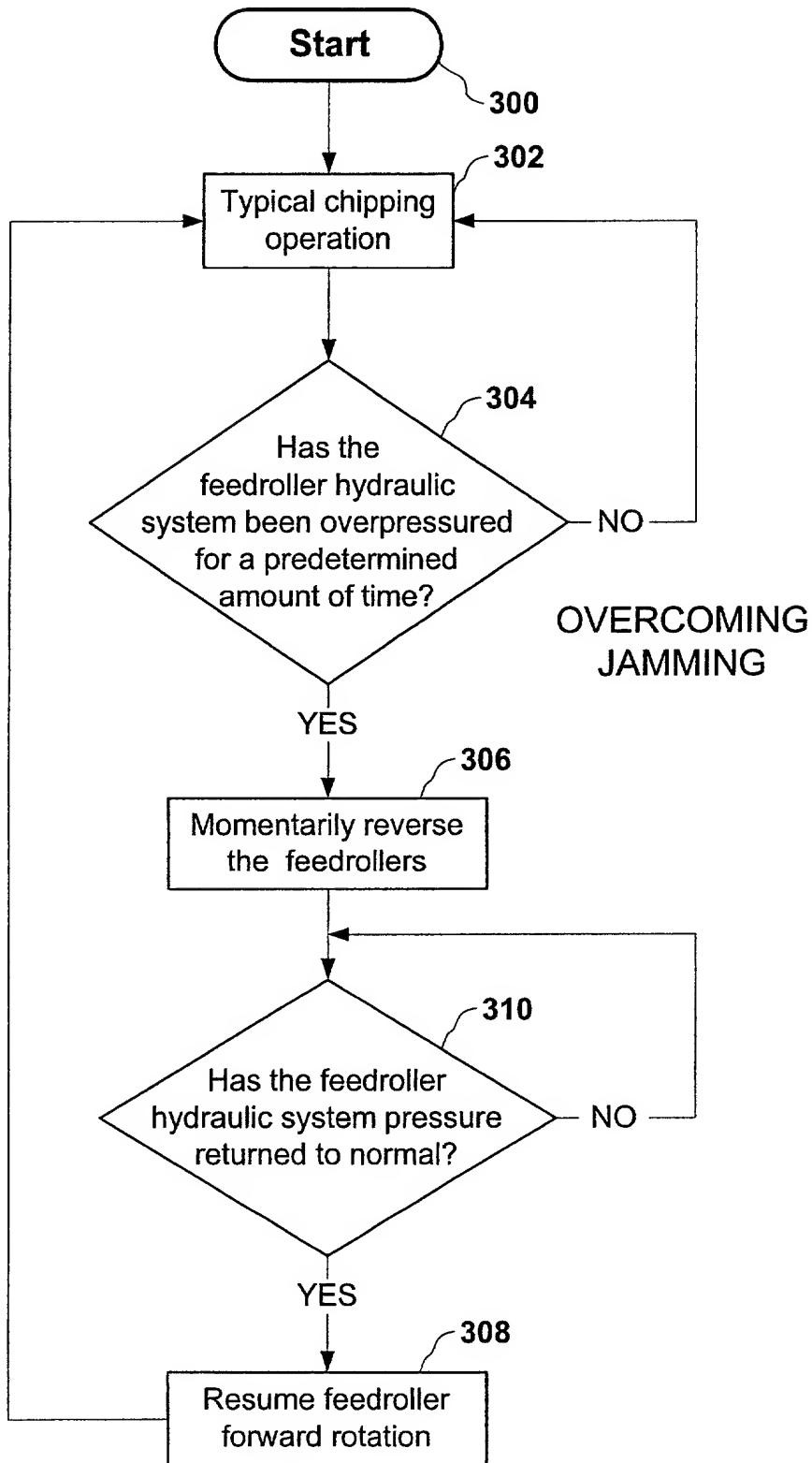
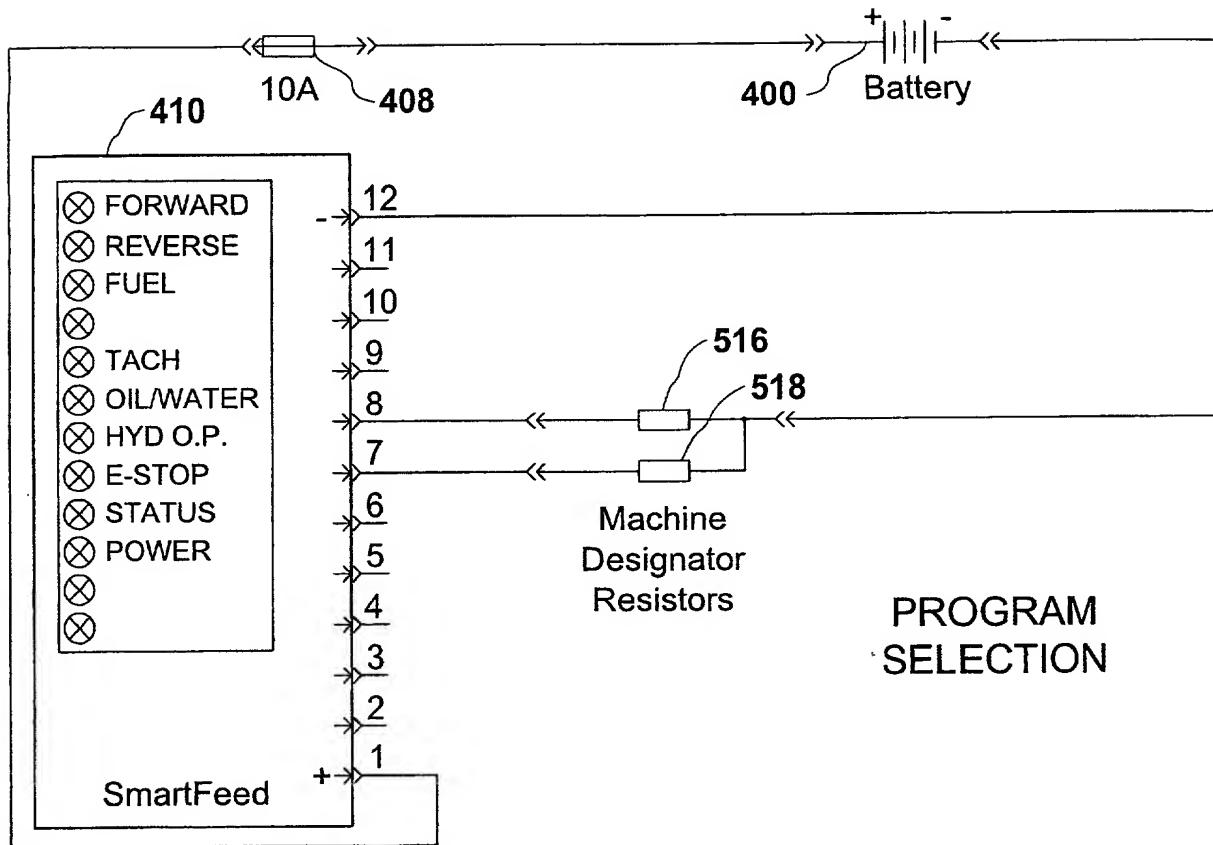
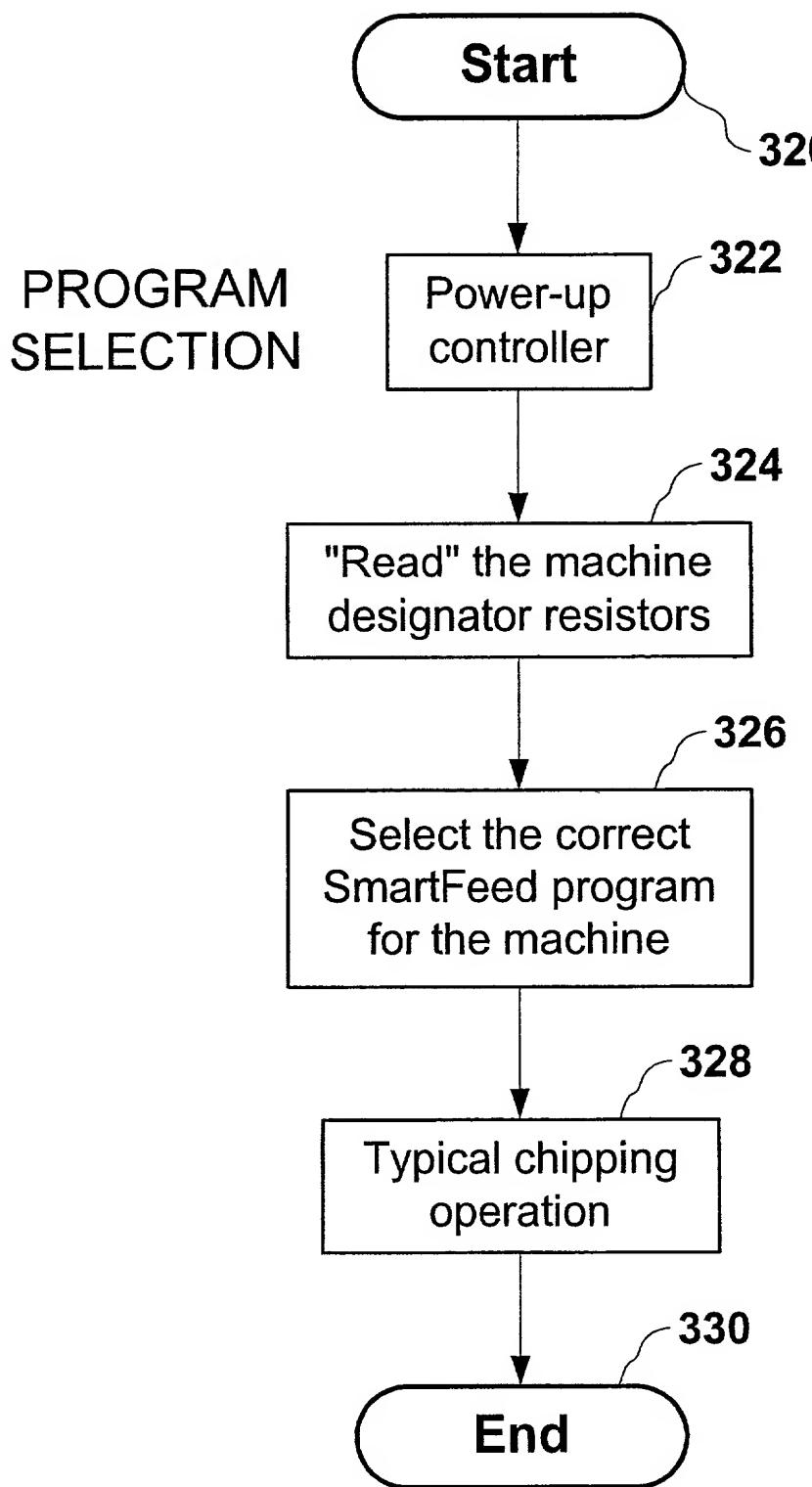


Fig. 24



*Fig. 25*



*Fig. 26*

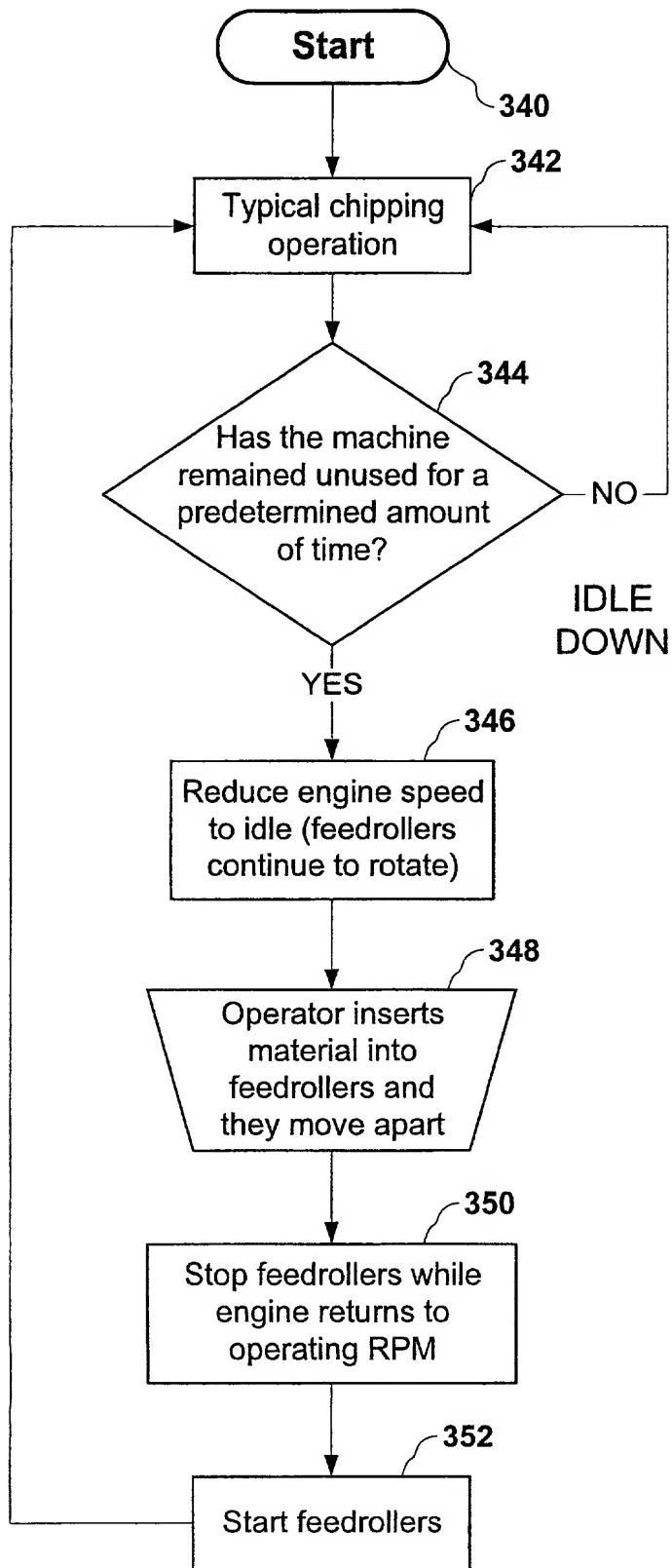


Fig. 27

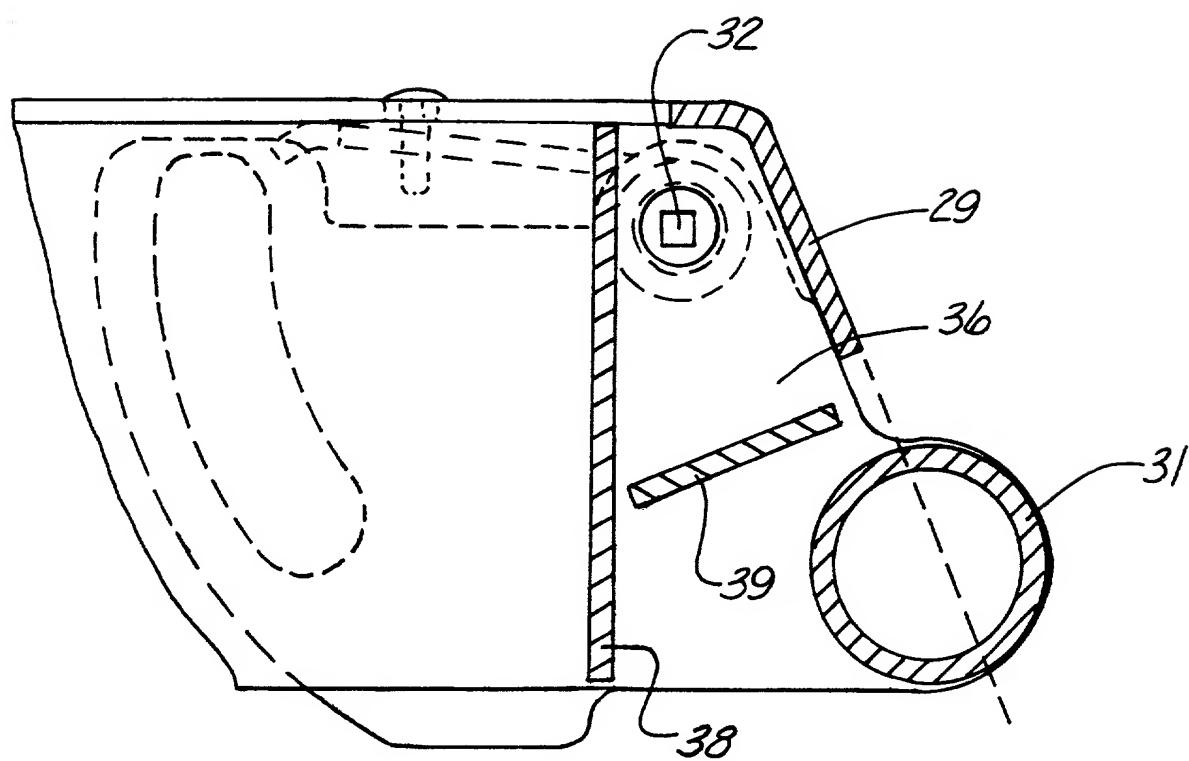


Fig. 28